

RESOLUTION 19-026

MOBILE AREA TRANSPORTATION STUDY (MATS)
METROPOLITAN PLANNING ORGANIZATION (MPO)

Unified Planning Work Program for FY 2020

WHEREAS, the Mobile Area Transportation Study (MATS) Metropolitan Planning Organization (MPO) is the organization designated by the Governor of the State of Alabama as being responsible, together with the State of Alabama, for implementing the applicable provisions of 23 USC 134, 135 (as amended by the FAST ACT Sections 1201, 1202 July 2012); 42 USC 7401 et seq.; 49 USC 5303, 5304; 23 CFR Parts 450; 40 CFR Parts 51 and 93; and,

WHEREAS, the U.S. Department of Transportation requires all urbanized areas, as established by the U.S. Bureau of the Census, doing area-wide urban transportation planning that involves more than one Department of Transportation operating administration, to submit a Unified Planning Work Program as a condition for meeting the provisions of Title 23, U.S. Code, Section 134; and,

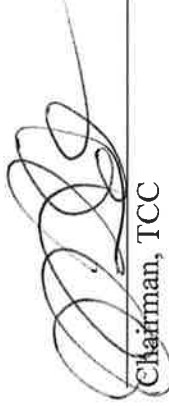
WHEREAS, consistent with the declaration of these provisions, the Mobile Area Transportation Study (MATS) Metropolitan Planning Organization (MPO), in cooperation with the Alabama Department of Transportation, has prepared a Unified Planning Work Program for Fiscal Year 2020 adopted on August 21, 2019; and subsequent public comment period as prescribed in the adopted Public Participation Procedures the below is to be amended to the FY 2020 Unified Planning Work Program:

Task 3.8.1.2- Game Day and Special Events study at USA (City of Mobile) - \$160,000 Federal
Task 3.8.1.3 - Access Management and Signal Operations Study on US 90 (ALDOT) \$116,000 Federal


WHEREAS, pursuant to its duties, functions, and responsibilities, the Mobile MPO, in session this 21st day of August, 2019, did review and evaluated the aforementioned Unified Planning Work Program amendments; now,

THEREFORE, BE IT RESOLVED by the Mobile MPO that the same does hereby endorse and adopt said Unified Planning Work Program.

ATTEST:



Chairman, TCC



Chairman, MPO